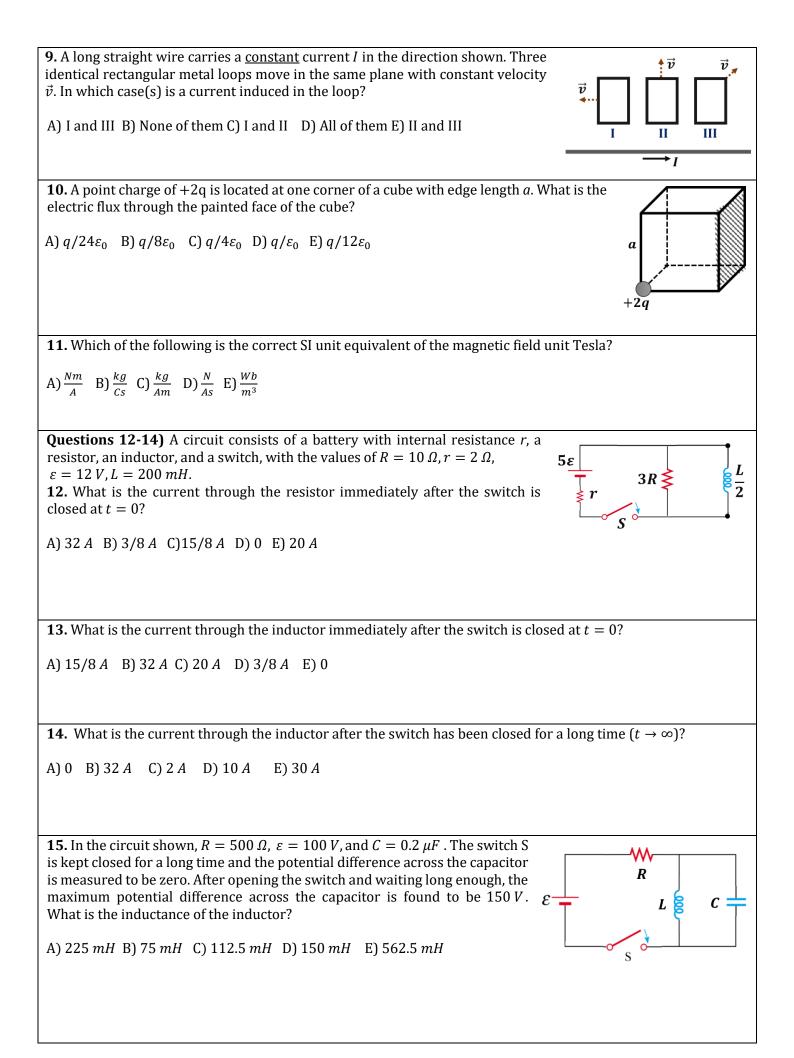
$V = \frac{V_{0}}{\kappa}; E = \frac{E_{0}}{\kappa}; U = \frac{U_{0}}{\kappa}; W = \int \vec{F} \cdot d\vec{r}; W = -\Delta U; I = \frac{dq}{dt}; I = nqv_{d}A; R = \rho\frac{\ell}{A}; \vec{J} = \sigma\vec{E}; R = \frac{dV}{l}; \sigma = \frac{1}{\rho}; J = \frac{1}{A}; \tau = RC; V = IR; I$ $I(t) = I_{0} \left(1 - e^{-t/\tau}\right); q(t) = Q_{0} e^{-t/\tau}; I(t) = I_{0} e^{-t/\tau}; q(t) = Q_{0} \left(1 - e^{-t/\tau}\right); P = IV = I^{2}R; \vec{F}_{B} = q\vec{v} \times \vec{B}; \vec{F}_{B} = I\vec{l} \times \vec{B}; \vec{\tau} = \vec{\mu} \times \vec{B}$ $\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}; U = -\vec{\mu}.\vec{B}; d\vec{B} = \frac{\mu_{0}I}{4\pi} \frac{d\vec{s} \times \hat{\tau}}{r^{2}}; \Phi_{B} = \int \vec{B} \cdot d\vec{A}; B = \mu_{0} \frac{N}{l}I = \mu_{0}nI; \phi\vec{B} \cdot d\vec{l} = \mu_{0}(I + I_{d}); I_{d} = \varepsilon_{0} \frac{d\phi_{E}}{dt}; \vec{\mu} = I\vec{A}; B = \mu$ $\varepsilon = \phi\vec{E} \cdot d\vec{l} = -\frac{d\phi_{B}}{dt}; \varepsilon_{L} = -N \frac{d\phi_{B}}{dt} = -L \frac{dI}{dt}; I_{rms} = \frac{I_{max}}{\sqrt{2}}; \Delta V_{rms} = \frac{\Delta V_{max}}{\sqrt{2}}; X_{L} = Lw; X_{C} = \frac{1}{cw}; tg\phi = \left(\frac{X_{L} - X_{C}}{R}\right); I_{max} = \frac{\Delta V_{max}}{Z}$ $w = \frac{1}{\sqrt{LC}}; Z = \sqrt{R^{2} + (X_{L} - X_{C})^{2}}; I_{rms}\Delta V_{rms}cos(\phi); \Delta v_{R} = \Delta V_{R}sin(wt); \Delta v_{C} = \Delta V_{C}sin\left(wt - \frac{\pi}{2}\right); \Delta v_{L} = \Delta V_{L}sin\left(wt + \frac{\pi}{2}\right)$ $\Delta V_{L} = I_{max}X_{L}; \Delta V_{C} = I_{max}X_{C}; \Delta V_{R} = I_{max}R; \omega_{0} = \frac{1}{\sqrt{LC}}; \tau = \frac{L}{R}; I = \frac{\varepsilon}{R} \left(1 - e^{-\frac{R}{L}t}\right); I = \frac{\varepsilon}{R} e^{-\frac{t}{\tau}}; U_{L} = \frac{1}{2}LI^{2}; u_{B} = \frac{1}{2}\left(\frac{B^{2}}{\mu_{0}}\right); M_{12} = N_{2}\frac{\phi_{12}}{I_{1}}$	YTU Physics Department 2024-2025 Spring Semester					
Question SneetAAAAAA09.00-11.40100 mNameThe 9th article of Student Disciplinary RegulationSurnameThe 9th article of Student Disciplinary RegulationStudent NoStudent NoSignatureStudent NoSignatureStudent NoSignatureStudent NoSignatureStudent S are NOT permitted to bring calcula mobile phones, smart watches and/or any ou unauthorized electronic devices into the exam root θ θ^0 30^0 37^0 45^0 53^0 60^0 90^0 $signaturek = \frac{1}{4\pi\epsilon_0} \cong 910^0 \frac{8m^2}{C^2}; \epsilon_0 \cong 9 \frac{10^{-12}x}{m}; e^{0.69} = 2; \mu_0 = 12 \frac{10^{-7}}{A}b0^1/23/5\sqrt{2}/24/5\sqrt{3}/24/5\sqrt{3}/21cos1\sqrt{3}/24/5\sqrt{3}/21\sqrt{3}/24/5\sqrt{3}/21cos1\sqrt{3}/24/5\sqrt{3}/21\sqrt{3}/24/5\sqrt{3}/21cos1\sqrt{3}/24/5\sqrt{3}/21\sqrt{3}/24/5\sqrt{3}/21cos1\sqrt{3}/24/5\sqrt{3}/21100^00^01100^00^01100^00^0110^00^00^0110^00^00^01^01^00^00^0$	FIZ1002 Physics-2 Final Exam					
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$ \frac{\cos 1}{E} = k \int \frac{dq}{r^2} \hat{r}; \ V = k \int \frac{dq}{r}; \ \Delta U = q \Delta V; \ \lambda = \frac{Q}{L} = \frac{dq}{dt}; \ \sigma = \frac{Q}{Q} = \frac{dq}{dA}; \ \rho = \frac{Q}{V} = \frac{dq}{dV}; \ \phi_E = \int \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ \phi_E - \int_A^B \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ \phi_E - \int_A^B \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ \phi_E - \int_A^B \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ \phi_E - \int_A^B \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ \phi_E - \int_A^B \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ \phi_E - \int_A^B \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ \phi_E - \int_A^B \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ \phi_E - \int_A^B \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ \phi_E - \int_A^B \vec{E} \cdot d\vec{A}; \ V_B - V_A = -\int_A^B \vec{E} \cdot d\vec{A}; \ e_E - V_A \vec{A}; \ V_E - V_E \vec{A}; \ V_E - V_E \vec{A}; \ V_E - V_E \vec{A}; \ V_E + V_E \vec{A}; \ V_E + V_E \vec{A}; \ V_E \vec{A}; \ V_E - V_E \vec{A}; \ V_E + V_E \vec{A}; \ V_E - V_E \vec{A}; \ V_E + V_E \vec{A}; \ V_E $	in 0 1/2 3/	0 11	$4/5 \sqrt{3}/2 = 1$			
$\begin{aligned} \Delta V &= Ed; \ E_y = \frac{\sigma}{2\epsilon_0}; \ E_i = \frac{\sigma}{\epsilon_0}; \ p = aq; \ \vec{t} = \vec{p} \times \vec{E}; \ U = -\vec{p} \cdot \vec{E}; \ C = \frac{ Q }{ \Delta V }; \ C = \frac{\epsilon_0 A}{a}; \ U = \frac{1}{2} CV^2; \ \frac{1}{c_eq} = \sum_i \frac{1}{c_i}; \ C_{eq} = \sum_i C_i; \ C = V = \frac{V_0}{\kappa}; \ E = \frac{\epsilon_0}{\kappa}; \ U = \frac{U_0}{\kappa}; \ W = \int \vec{F} \cdot d\vec{r}; \ W = -\Delta U; \ I = \frac{dq}{dt}; \ I = nqv_d A; \ R = \rho \frac{\ell}{A}; \ \vec{J} = \sigma \vec{E}; \ R = \frac{dV}{I}; \ \sigma = \frac{1}{\rho}; \ J = \frac{1}{a}; \ \tau = RC; \ V = IR; I \\ I(t) = I_0 \left(1 - e^{-t/\tau}\right); \ q(t) = Q_0 e^{-t/\tau}; \ I(t) = I_0 e^{-t/\tau}; \ q(t) = Q_0 \left(1 - e^{-t/\tau}\right); \ P = IV = I^2R; \ \vec{F}_B = q\vec{v} \times \vec{B}; \ \vec{F}_B = I\vec{1} \times \vec{B}; \ \vec{\tau} = \vec{\mu} \times \vec{B} \\ \vec{F} = q\vec{E} + q\vec{v} \times \vec{B}; \ U = -\vec{\mu} \cdot \vec{B}; \ d\vec{B} = \frac{\mu_0 d\vec{S} \times \vec{r}}{dt}; \ \varphi_B = \int \vec{B} \cdot d\vec{A}; \ B = \mu_0 \frac{N}{t} I = \mu_0 nI; \ \phi \vec{B} \cdot d\vec{I} = \mu_0 (I + I_d); \ I_d = \epsilon_0 \frac{d\phi_E}{dt}; \ \vec{\mu} = I\vec{A}; \ B = \mu \\ \epsilon = \phi \vec{E} \cdot d\vec{I} = -\frac{d\phi_B}{dt}; \ \epsilon_L = -N \frac{d\phi_B}{dt} = -L \frac{d}{dt}; \ I_{rms} = \frac{lmax}{\sqrt{2}}; \ \Delta V_{rms} = \frac{\Delta V_{max}}{\sqrt{2}}; \ X_L = Lw; \ X_C = \frac{1}{c_w}; \ tg\phi = \left(\frac{X - X}{R}\right); \ I_{max} = \frac{\Delta V_{max}}{R} \\ w = \frac{1}{\sqrt{Lc}}; \ Z = \sqrt{R^2 + (X_L - X_C)^2}; \ p > I_{rms} \Delta V_{rms} \cos(\phi); \ \Delta v_R = \Delta V_R \sin(wt); \ \Delta v_C = \Delta V_C \sin(wt - \frac{\pi}{2}); \ \Delta v_L = \Delta V_L \sin(wt + \frac{\pi}{2}) \\ \Delta V_L = I_{max}X_L; \ \Delta V_C = I_{max}X_C; \ \Delta V_R = I_{max}R; \ \omega_0 = \frac{1}{\sqrt{Lc}}; \ T = \frac{R}{R}; \ I = \frac{e}{R} \left(1 - e^{-\frac{R}{L}}\right); \ I = \frac{e}{R} e^{-\frac{t}{L}}; \ U_L = \frac{1}{2}L^{12}; \ u_B = \frac{1}{2} \left(\frac{B^2}{\mu_0}\right; \ M_L = N_2 \frac{d\mu_L}{m_L}; \\ L = -M \frac{dI_2}{dt}; \ \epsilon_2 = -M \frac{dI_1}{dt}; \ U_C = \frac{Q^2}{2c'}; \ Q = Q_{max}cos(\omega t + \phi); \ I_{max} = \omega Q_{max}; \ \varepsilon_{ind} = -Bl \frac{dx}{dt} = -Blv; \ P = F_{app}v; \ \Delta V_2 = \frac{N_2}{N_1} \\ \frac{dH}{dt} = -3K N \end{aligned}$ 1. A solenoid with radius R and number of turns N lies along its own axis in a timevarying magnetic field with dB/dt=3K, where K is a positive constant. At t=0, B=0. What are the magnitudes of the magnetic flux through one turn of the solenoid at any time t? A) $6NK\pi R^2t; 9NK\pi R^2$ B) $6K\pi R^2t; 9NK\pi R^2$ D) $3K\pi R^2t; 3N$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$					
$V = \frac{v_0}{\kappa}; E = \frac{E_0}{\kappa}; U = \frac{u_0}{\kappa}; W = \int \vec{r} \cdot d\vec{r}; W = -\Delta U; I = \frac{dq}{dt}; I = nqv_d A; R = \rho_A^{\vec{r}}, \vec{j} = \sigma \vec{E}; R = \frac{AV}{l}; \sigma = \frac{1}{\rho}; J = \frac{1}{A}; \tau = RC; V = IR; I$ $I(t) = I_0 \left(1 - e^{-t/\tau}\right); q(t) = Q_0 e^{-t/\tau}; I(t) = I_0 e^{-t/\tau}; q(t) = Q_0 \left(1 - e^{-t/\tau}\right); P = IV = I^2R; \vec{F}_B = q\vec{v} \times \vec{B}; \vec{F}_B = I\vec{l} \times \vec{B}; \vec{\tau} = \vec{\mu} \times \vec{B}$ $\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}; U = -\vec{\mu}. \vec{B}; d\vec{B} = \frac{\mu_0 I}{4\pi} \frac{dSx^{\vec{r}}}{r^2}; \Phi_B = \int \vec{B} \cdot d\vec{A}; B = \mu_0 \frac{N}{l} I = \mu_0 nI; \phi \vec{B} \cdot d\vec{l} = \mu_0(I + I_d); I_d = \varepsilon_0 \frac{d\phi E}{dt}; \vec{\mu} = I\vec{A}; B = \mu$ $\varepsilon = \phi \vec{E} \cdot d\vec{l} = -\frac{d\phi B}{dt}; \varepsilon_L = -N \frac{d\phi B}{dt} = -L \frac{dI}{dt}; I_{rms} = \frac{I_{max}}{\sqrt{2}}; \Delta V_{rms} = \frac{\Delta V_{max}}{\sqrt{2}}; X_L = Lw; X_C = \frac{1}{cw}; tg\phi = \left(\frac{X_L - C}{R}\right); I_{max} = \frac{\Delta V_{max}}{Z}$ $w = \frac{1}{\sqrt{LC}}; Z = \sqrt{R^2 + (X_L - X_C)^2}; I_{rms}\Delta V_{rms}cos(\phi); \Delta v_R = \Delta V_R sin(wt); \Delta v_C = \Delta V_C sin(wt - \frac{\pi}{2}); \Delta v_L = \Delta V_L sin(wt + \frac{\pi}{2})$ $\Delta V_L = I_{max}X_L; \Delta V_C = I_{max}X_C; \Delta V_R = I_{max}R; \omega_0 = \frac{1}{\sqrt{LC}}; \tau = \frac{L}{R}; I = \frac{\varepsilon}{R} \left(1 - e^{-\frac{R}{L}t}\right); I = \frac{\varepsilon}{R} e^{-\frac{t}{\tau}}; U_L = \frac{1}{2}LI^2; u_B = \frac{1}{2} \left(\frac{B^2}{\mu_0}\right); M_{12} = N_2 \frac{\Phi_{12}}{N_1}$ $s_1 = -M \frac{dI_2}{dt}; \varepsilon_2 = -M \frac{dI_1}{dt}; U_C = \frac{Q^2}{2C}; Q = Q_{max}cos(\omega t + \phi); I_{max} = \omega Q_{max}; \varepsilon_{ind} = -Bl \frac{dx}{dt} = -Blv; P = F_{app} v; \Delta V_2 = \frac{N_2}{N_1} \Delta V_2 = N_2$						
$I(t) = I_0 \left(1 - e^{-t/\tau}\right); q(t) = Q_0 e^{-t/\tau}; I(t) = I_0 e^{-t/\tau}; q(t) = Q_0 \left(1 - e^{-t/\tau}\right); P = IV = I^2 R; \vec{F}_B = q\vec{v} \times \vec{B}; \vec{F}_B = I\vec{l} \times \vec{B}; \vec{\tau} = \vec{\mu} \times \vec{B}$ $\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}; U = -\vec{\mu} \cdot \vec{B}; d\vec{B} = \frac{\mu_0 l}{4\pi} \frac{d\vec{S} \times \vec{r}}{r^2}; \phi_B = \int \vec{B} \cdot d\vec{A}; B = \mu_0 \frac{N}{l} I = \mu_0 nI; \oint \vec{B} \cdot d\vec{l} = \mu_0 (I + I_d); I_d = \varepsilon_0 \frac{d\phi_E}{dt}; \vec{\mu} = I\vec{A}; B = \mu_0 \vec{E} + q\vec{v} \times \vec{B}; U = -\vec{R}, \vec{E} = -N \frac{d\phi_B}{dt} = -L \frac{dt}{dt}; I_{rms} = \frac{I_{max}}{\sqrt{2}}; \Delta V_{rms} = \frac{\Delta V_{max}}{\sqrt{2}}; X_L = Lw; X_C = \frac{1}{Cw}; tg\phi = \left(\frac{X_L - X_C}{R}\right); I_{max} = \frac{\Delta V_{max}}{Z}$ $w = \frac{1}{\sqrt{LC}}; Z = \sqrt{R^2 + (X_L - X_C)^2}; = I_{rms} \Delta V_{rms} cos(\phi); \Delta v_R = \Delta V_R sin(wt); \Delta v_C = \Delta V_C sin\left(wt - \frac{\pi}{2}\right); \Delta v_L = \Delta V_L sin\left(wt + \frac{\pi}{2}\right)$ $\Delta V_L = I_{max} X_L; \Delta V_C = I_{max} X_C; \Delta V_R = I_{max} R; \omega_0 = \frac{1}{\sqrt{LC}}; \tau = \frac{L}{R}; I = \frac{\varepsilon}{R} \left(1 - e^{-\frac{R}{L}t}\right); I = \frac{\varepsilon}{R} e^{-\frac{t}{t}}; U_L = \frac{1}{2}LI^2; u_B = \frac{1}{2} \left(\frac{B^2}{\mu_0}\right); M_{12} = N_2 \frac{\phi_{12}}{I_1}$ $\varepsilon_1 = -M \frac{dI_2}{dt}; \varepsilon_2 = -M \frac{dI_1}{dt}; U_C = \frac{Q^2}{2C}; Q = Q_{max} cos(\omega t + \phi); I_{max} = \omega Q_{max}; \varepsilon_{ind} = -BI \frac{dx}{dt} = -BIv; P = F_{app}v; \Delta V_2 = \frac{N_2}{N_1} \Delta V_2 = \frac{N_2}{N_1} \Delta V_2$ A) 6NK $\pi R^2 t; 9NK \pi R^2$ B) 6K $\pi R^2 t; 9NK \pi R^2$ D) 3K $\pi R^2 t; 3NK \pi R^2$	$ \Delta V = Ed; \ E_y = \frac{\sigma}{2\varepsilon_0}; \ E_i = \frac{\sigma}{\varepsilon_0}; \ p = aq; \ \vec{\tau} = \vec{p} \times \vec{E}; \ U = -\vec{p}. \vec{E}; \ C = \frac{ Q }{ \Delta V }; \ C = \frac{\varepsilon_0 A}{d}; \ U = \frac{1}{2}CV^2; \ \frac{1}{c_{eq}} = \sum_i \frac{1}{c_i}; \ C_{eq} = \sum_i C_i; \ C = \kappa C_0$					
$\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}; U = -\vec{\mu} \cdot \vec{B}; d\vec{B} = \frac{\mu_0 l}{4\pi} \frac{d\vec{S} \times \vec{r}}{r^2}; \Phi_B = \int \vec{B} \cdot d\vec{A}; B = \mu_0 nl; \phi \vec{B} \cdot d\vec{l} = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); l_d = \varepsilon_0 \frac{d\phi_E}{dt}; \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A}; B = \mu_0 (l + l_d); \mu = l\vec{A};$	r · · · · ·					
$\varepsilon = \oint \vec{E} \cdot d\vec{l} = -\frac{d\phi_B}{dt}; \\ \varepsilon_L = -N\frac{d\phi_B}{dt} = -L\frac{dl}{dt}; \\ I_{rms} = \frac{I_{max}}{\sqrt{2}}; \\ \Delta V_{rms} = \frac{\Delta V_{max}}{\sqrt{2}}; \\ X_L = Lw; \\ X_C = \frac{1}{Cw}; \\ tg\phi = \left(\frac{X_L - X_C}{R}\right); \\ I_{max} = \frac{\Delta V_{max}}{2}; \\ w = \frac{1}{\sqrt{LC}}; \\ Z = \sqrt{R^2 + (X_L - X_C)^2}; \\ \phi > = I_{rms} \Delta V_{rms} cos(\phi); \\ \Delta v_R = \Delta V_R sin(wt); \\ \Delta v_C = \Delta V_C sin\left(wt - \frac{\pi}{2}\right); \\ \Delta v_L = I_{max} X_L; \\ \Delta V_C = I_{max} X_C; \\ \Delta V_R = I_{max} R; \\ \omega_0 = \frac{1}{\sqrt{LC}}; \\ \tau = \frac{L}{R}; \\ I = \frac{\varepsilon}{R} \left(1 - e^{-\frac{R}{L}t}\right); \\ I = \frac{\varepsilon}{R} e^{-\frac{t}{\tau}}; \\ U_L = \frac{1}{2}LI^2; \\ u_B = \frac{1}{2}\left(\frac{B^2}{\mu_0}\right); \\ M_{12} = N_2\frac{\phi_{12}}{I_1}; \\ \varepsilon_1 = -M\frac{dI_2}{dt}; \\ \varepsilon_2 = -M\frac{dI_1}{dt}; \\ U_C = \frac{Q^2}{2c}; \\ Q = Q_{max}cos(\omega t + \phi); \\ I_{max} = \omega Q_{max}; \\ \varepsilon_{ind} = -Bl\frac{dx}{dt} = -Blv; \\ P = F_{app}v; \\ \Delta V_2 = \frac{N_2}{N_1}\Delta V$						
$w = \frac{1}{\sqrt{LC}}; Z = \sqrt{R^2 + (X_L - X_C)^2}; = I_{rms} \Delta V_{rms} cos(\phi); \Delta v_R = \Delta V_R sin(wt); \Delta v_C = \Delta V_C sin\left(wt - \frac{\pi}{2}\right); \Delta v_L = \Delta V_L sin\left(wt + \frac{\pi}{2}\right); \Delta v_L = I_{max} X_L; \Delta V_C = I_{max} X_C; \Delta V_R = I_{max} R; \omega_0 = \frac{1}{\sqrt{LC}}; \tau = \frac{L}{R}; I = \frac{\varepsilon}{R} \left(1 - e^{-\frac{R}{L}t}\right); I = \frac{\varepsilon}{R} e^{-\frac{t}{\tau}}; U_L = \frac{1}{2}LI^2; u_B = \frac{1}{2} \left(\frac{B^2}{\mu_0}\right); M_{12} = N_2 \frac{\phi_{12}}{I_1}; \varepsilon_1 = -M \frac{dI_2}{dt}; \varepsilon_2 = -M \frac{dI_1}{dt}; U_C = \frac{Q^2}{2C}; Q = Q_{max} cos(\omega t + \phi); I_{max} = \omega Q_{max}; \varepsilon_{ind} = -Bl \frac{dx}{dt} = -Blv; P = F_{app}v; \Delta V_2 = \frac{N_2}{N_1} \Delta V_2 = \frac{N_2}{N_1} \Delta V_2$ 1. A solenoid with radius R and number of turns N lies along its own axis in a time-varying magnetic field with dB/dt=3K, where K is a positive constant. At t=0, B=0. What are the magnitudes of the magnetic flux through one turn of the solenoid and the electromotive force (emf) induced in the solenoid at any time t? A) $6NK\pi R^2 t; 9NK\pi R^2$ B) $6K\pi R^2 t; 9NK\pi R^2$ D) $3K\pi R^2 t; 3NK\pi R^2$	$\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}; U = -\vec{\mu}.\vec{B}; d\vec{B} = \frac{\mu_0 I}{4\pi} \frac{d\vec{s} \times \vec{r}}{r^2}; \Phi_B = \int \vec{B} \cdot d\vec{A}; B = \mu_0 \frac{N}{l} I = \mu_0 nI; \ \oint \vec{B} \cdot d\vec{l} = \mu_0 (I + I_d); \ I_d = \varepsilon_0 \frac{d\phi_E}{dt}; \vec{\mu} = I\vec{A}; \ B = \mu_0 nI$					
$\Delta V_L = I_{max} X_L; \Delta V_C = I_{max} X_C; \Delta V_R = I_{max} R; \ \omega_0 = \frac{1}{\sqrt{LC}}; \tau = \frac{L}{R}; I = \frac{\varepsilon}{R} \left(1 - e^{-\frac{R}{L}t}\right); I = \frac{\varepsilon}{R} e^{-\frac{t}{\tau}}; U_L = \frac{1}{2}LI^2; \ u_B = \frac{1}{2} \left(\frac{B^2}{\mu_0}\right); \ M_{12} = N_2 \frac{\Phi_{12}}{I_1}$ $\varepsilon_1 = -M \frac{dI_2}{dt}; \ \varepsilon_2 = -M \frac{dI_1}{dt}; \ U_C = \frac{Q^2}{2C}; \ Q = Q_{max} cos(\omega t + \varphi); \ I_{max} = \omega Q_{max}; \ \varepsilon_{ind} = -Bl \frac{dx}{dt} = -Blv; \ P = F_{app}v; \ \Delta V_2 = \frac{N_2}{N_1} \Delta V_2 = \frac{N_2}{N_1} \Delta V_2$ 1. A solenoid with radius R and number of turns N lies along its own axis in a time- varying magnetic field with dB/dt=3K, where K is a positive constant. At t=0, B=0. What are the magnitudes of the magnetic flux through one turn of the solenoid and the electromotive force (emf) induced in the solenoid at any time t? A) $6NK\pi R^2 t; 9NK\pi R^2$ B) $6K\pi R^2 t; 9NK\pi R^2$ D) $3K\pi R^2 t; 3NK\pi R^2$						
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B) $6K\pi R^2 t$; $6NK\pi R^2$ C) $9K\pi R^2 t$; $9NK\pi R^2$ D) $3K\pi R^2 t$; $3NK\pi R^2$	varying magnetic field with dB/dt=3K, where K is a positive constant. At t=0, B=0. What are the magnitudes of the magnetic flux through one turn of the solenoid and the electromotive force (emf) induced in the solenoid at any time t? $\vec{B} \rightarrow R$ $\vec{D} = R$					
C) $9K\pi R^2 t$; $9NK\pi R^2$ D) $3K\pi R^2 t$; $3NK\pi R^2$						
	C) $9K\pi R^2 t$; $9NK\pi R^2$					
$ E 3NK\pi R^2 t; 3NK\pi R^2$						
) 3NKπR ² t; 3NKπI					
V_P V_P V_P V_F V_F V_F V_A . A uniform current <i>I</i> begins to flow through the Helmholtz coils at time <i>t</i> the distance between the plates is <i>d</i> , and a voltage V_P is applied between the Which of the following is correct? A) To determine the e/m ratio using the Lorentz force, the current in the coils reflections of the context of the cont	escent screen placed between an electron gun. $_{F}$ are accelerated by a voltage Helmholtz coils at time $t > 0$. V_{P} is applied between them.					

I = 0

B) At t = 0, plate number 2 is negatively charged. C) If the current flows counterclockwise through the coils, the beam deflects downward.

D) The magnitude of V_P does not affect the amount of horizontal deflection. E) The magnitude of V_A is inversely proportional to the kinetic energy of the beam.

Questions 3-4) A circular silver wire with resistance R and radius 2r is placed in a uniform magnetic field perpendicular to its plane. The magnetic field strength increases from t = 0 to t = T according to the relation $B = B_0 \left(3 + \frac{5t}{T}\right)$, where t is in seconds and B_0 is a positive constant. **3**. What is the magnetic flux in Wb through the wire at $t = \frac{T}{r}$? A) $32B_0\pi r^2$ B) $16B_0\pi r^2$ C) $12B_0\pi r^2$ D) $8B_0\pi r^2$ E) $36B_0\pi r^2$ **4.** Which of the following correctly gives the total induced current in the loop from t = 0 to t = T? A) $4B_0\pi r^2/RT$ counterclockwise B) $20B_0\pi r^2/RT$ clockwise C) $4B_0\pi r^2/RT$ clockwise D) $16B_0\pi r^2/RT$ counterclockwise E) $20B_0\pi r^2/RT$ counterclockwise 5. What is the induced electric field vector at point P? A) $5B_0r/2T(-\hat{\imath})$ B) $10B_0r/T(\hat{\imath})$ C) $5B_0r/2T(\hat{\imath})$ D) $2B_0r/T(\hat{\imath})$ E) $10B_0r/T(-\hat{\imath})$ **Ouestions 6-7)** Three infinitely large insulating plates are placed parallel to each other with equal spacing *d*. The surface charge densities of the plates are $\sigma_1 = 10 \ \mu C/m^2$, $\sigma_2 = -20 \ \mu C/m^2$ and $\sigma_3 = 5 \ \mu C/m^2$, respectively. 6. What is the electric field vector in region A, in units of V/m? C ₿ A) $\frac{5}{18}10^{6}(-\hat{\imath})$ B) $\frac{35}{18}10^{6}(\hat{\imath})$ C) $\frac{5}{18}10^{6}(\hat{\imath})$ D) $\frac{45}{18}10^{6}(-\hat{\imath})$ E) $\frac{25}{18}10^{6}(\hat{\imath})$ **7.** What is the potential difference $|E_E - E_F|$ between points E and F in region B? A) $\frac{45}{9}$ 10⁶ B) $\frac{5}{9}$ 10⁶ C) $\frac{15}{18}$ 10⁶ D) $\frac{25}{9}$ 10⁶ E) $\frac{50}{18}$ 10⁶ 8. Laboratory Question A conducting rod of length L=2.5 cm is placed perpendicular to a uniform magnetic field (B=0.5 T), located in the shaded region of the xy-plane. The conducting rod is vertically attached to the end of a dynamometer and connected horizontally via weightless wires to a battery and an ammeter. The conducting rod, which has negligible mass, carries a steady current *I*. According to the analysis of a researcher using this experimental setup, which of the following statements is incorrect? B A) If $\vec{B} = B\hat{k}$ the conducting rod moves downward. B) As the current through the conducting rod increases, the rod continues to move downward. C) If the current through the rod is 8 *A* and the dynamometer points 104 *mN*, the absolute error is 4 *mN*. D) If the current through the rod is 4 *A* and the dynamometer points 52 *mN*, the relative error is 0.01. E) If the current through the rod is 2 *A*, the dynamometer points 25 *mN*.



Questions 16-17) A toroid with rectangular cross-section has *N* turns, an outer N radius of 3R, an inner radius of 3R/2, and a height d. **16.** What is the self-inductance of the toroid? A) $\frac{N\mu_0 d}{2\pi} ln(2)$ 3*R* B) $\frac{N^2 \mu_0}{4\pi} ln\left(\frac{2}{3}\right)$ 3R/2C) $\frac{\frac{4\pi}{N^2 \mu_0}}{2\pi} ln\left(\frac{3}{2}\right)$ D) $\frac{N^2 \mu_0 d}{2\pi} ln(2)$ E) $\frac{N\mu_0}{2\pi} ln\left(\frac{2}{3}\right)$ 17. If a constant current *I* flows through the toroid, which of the following correctly gives the energy stored in the toroid? A) $\frac{N^2 \mu_0 dI^2}{8\pi} ln\left(\frac{2}{3}\right)$ B) $\frac{N \mu_0 dI^2}{2\pi} ln(2)$ C) $\frac{N \mu_0 I^2}{2\pi} ln\left(\frac{2}{3}\right)$ D) $\frac{N^2 \mu_0 I^2}{4\pi} ln\left(\frac{2}{3}\right)$ E) $\frac{N^2 \mu_0 dI^2}{4\pi} ln(2)$ **18.** An ideal transformer has 200 primary turns and 100 secondary turns. If a current of 1.2 A and a potential difference of 80 V is applied across the primary circuit, what is the current in the secondary circuit? A) 2.4 A B) 0.6 A C) 4.8 A D) 8/3 A E) 3 A Questions 19-20) In the given circuit, a resistor, inductor, and capacitor are connected in series to an alternating voltage source. $R = 3\Omega \quad X_L = 6\Omega \quad X_C = 2\Omega$ **19.** Which of the following correctly gives the circuit's impedance and effective current? $5\sqrt{2} \sin 100\pi t$ A) 5Ω ; 2A B) 11 Ω; $\sqrt{2}$ A C) 11 Ω ; $\sqrt{2} A$ D) $5\sqrt{2} \Omega$; 1 A E) 5 Ω; 1 A **20.** Which of the following correctly gives the phase difference in the circuit shown? A) 53⁰ B) 37⁰ C) 0^{0} D) 45⁰ E) 90⁰

1-D	11-В
2-A	12-C
3-В	13-Е
4-E	14-E
5-A	15-C
6-C	16-D
7-D, E	17-Е
8-D	18-A
9-E	19-Е
10-E	20-A